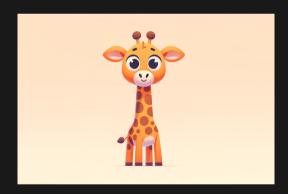
COMP6771



Lecture 7.1

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- Iheritance: ability to create new classes based on existing ones
 - Supported by class derivation
- Polymorphism: allows objects of a subclass to be used as if they were objects of a base class
 - Supported via virtual functions
- **Dynamic binding**: run-time resolution of the appropriate function to invoke based on the type of the object
 - Closely related to polymorphism
 - Supported via virtual functions

XOO Tenets Of C++

- Don't pay for what you don't use
 - C++ Supports OOP
 - No runtime performance penalty
 - C++ supports generic programming with the STL and templates
 - No runtime performance penalty
 - Polymorphism is extremely powerful, and we need it in C++
 - Do we need polymorphism at all when using inheritance?
 - Answer: sometimes
 - But how do we do so, considering that we don't want to make anyone who doesn't use it pay a performance penalty
- One of the guiding principles of C++ is "You don't pay for what you don't use"

Q Inheritance In C++

```
1 class BaseClass {
2  public:
3   int get_int_member() { return int_member_; }
4   std::string get_class_name() {
5    return "BaseClass"
6  };
7
8  private:
9  int int_member_;
10  std::string string_member_;
11 }
```

```
1 class SubClass: public BaseClass {
2  public:
3   std::string get_class_name() {
4    return "SubClass";
5  }
6
7  private:
8   std::vector<int> vector_member_;
9   std::unique_ptr<int> ptr_member_;
10 }
```

○ Inheritance In C++

- To inherit off classes in C++, we use "class DerivedClass: public BaseClass"
- Visibility can be one of:
 - public (generally use this unless you have good reason not to)
 - o If you don't want public, you should (usually) use composition
 - protected
 - private
- Visibility is the maximum visibility allowed
 - If you specify ": private BaseClass", then the maximum visibility is private
 - Any BaseClass members that were public or protected are now private

Q Inheritance In C++

Memory Layout

BaseClass object		SubClass object
int_member_	BaseClass subobject	int_member_
string_member_		string_member_
	SubClass subobject	vector_member_
		ptr_member_

```
1 #include <string>
 2 #include <iostream>
 4 class BaseClass {
 5 public:
     int get_member() { return member_; }
     std::string get_class_name() {
       return "BaseClass";
     };
10
    private:
11
     int member ;
13 };
15 class SubClass: public BaseClass {
   public:
     std::string get_class_name() {
17
       (void) subclass_data_;
       return "SubClass";
21
    private:
     int subclass_data_;
24 };
26 void print_class_name(BaseClass base) {
     std::cout << base.get_class_name()</pre>
               << ' ' << base.get_member()
               << '\n';
30 }
32 int main() {
    BaseClass base class;
    SubClass subclass;
     print_class_name(base_class);
     print_class_name(subclass);
36
37 }
```

How many bytes is a BaseClass instance?

How many bytes is a SubClass instance?

How can the compiler allocate space for it on the stack, when it doesn't know how big it could be?

The answer: since we care about performance, a BaseClass can only store a BaseClass, not a SubClass

If we try to fill that value with a SubClass, then it just fills it with the BaseClass subobject, and drops the SubClass subobject

This is called the **object slicing problem**

The **solution** to this is to use references/pointers (preferably references) to the baseclass

```
1 #include <string>
 2 #include <iostream>
 4 class BaseClass {
 5 public:
     int get_member() { return member_; }
     std::string get_class_name() {
       return "BaseClass";
     };
10
    private:
11
     int member ;
13 };
15 class SubClass: public BaseClass {
   public:
     std::string get_class_name() {
17
       (void) subclass_data_;
18
       return "SubClass";
21
    private:
     int subclass_data_;
24 };
26 void print_class_name(BaseClass& base) {
     std::cout << base.get_class_name()</pre>
               << ' ' << base.get_member()
               << '\n';
30 }
32 int main() {
    BaseClass base class;
    SubClass subclass;
    print_class_name(base_class);
36
     print_class_name(subclass);
37 }
```

🧩 More Problems

```
1 class BaseClass {
2 public:
     int get member() { return member ; }
     std::string get_class_name() {
     return "BaseClass";
    private:
     int member ;
11 class SubClass: public BaseClass {
12 public:
     std::string get_class_name() {
      return "SubClass";
14
15
16
17
   private:
     int subclass data;
19 }
```

- How does the compiler decide which version of get_class_name to call?
 - When does the compiler decide this? Compile or runtime?
- How can it ensure that calling get_member doesn't have similar overhead?

Virtual & Override

```
void print_stuff(const BaseClass& base) {
  std::cout << base.get_class_name() << '
  int main() {
  SubClass subclass;
  print_stuff(subclass);
}</pre>
```

By default, C++ will call "get_class_name()" of the BaseClass.

However, if the base class has the function marked as **virtual**, it will happily look toward the derived class.

Virtual & Override

For example:

```
1 class BaseClass {
2  public:
3   int get_member() { return member_; }
4   virtual std::string get_class_name() {
5    return "BaseClass"
6  };
7
8  private:
9  int member_;
10 }
```

```
1 class SubClass: public BaseClass {
2  public:
3   std::string GetClassName() override {
4    return "SubClass";
5  }
6
7  private:
8   int subclass_data_;
9 }
```

Note the use of the **override** keyword to.

Virtual & Override

- While override isn't required by the compiler, you should always use it
- Override fails to compile if the function doesn't exist in the base class. This helps with:
 - Typos
 - Refactoring
 - Const / non-const methods
 - Slightly different signatures



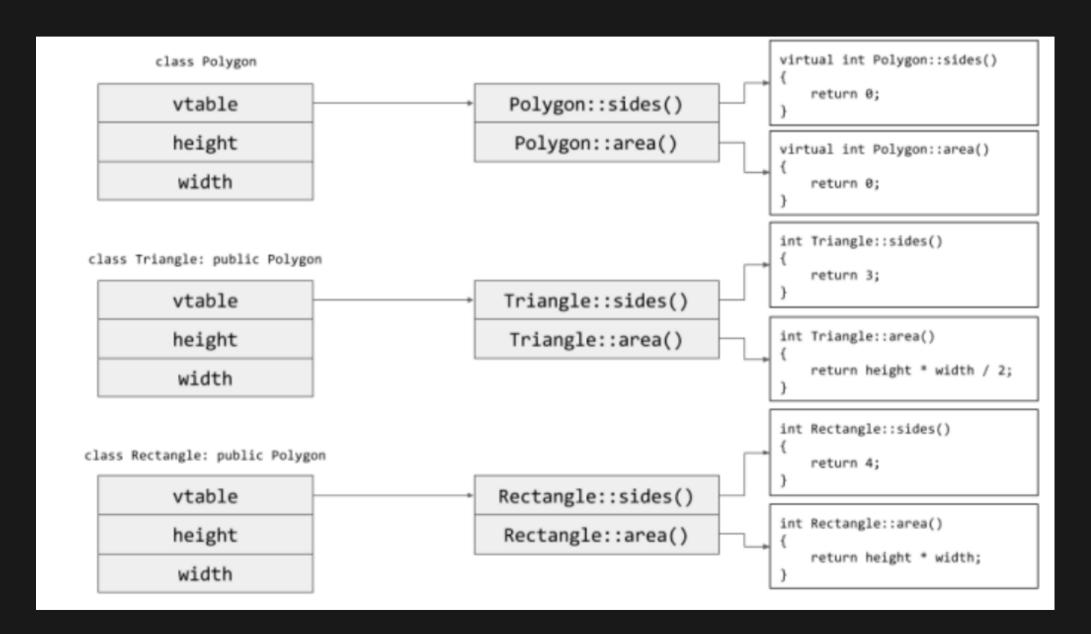
Let's explore some outputs wiht virtual members

```
1 #include <iostream>
 2 #include <string>
 4 class BaseClass {
 5 public:
    virtual std::string get_class_name() const {
       return "BaseClass";
     };
     virtual ~BaseClass() {
      std::cout << "Destructing base class\n";</pre>
13 };
15 class SubClass: public BaseClass {
16 public:
     std::string get_class_name() const override {
       return "SubClass";
   ~SubClass() {
      std::cout << "Destructing subclass\n";</pre>
24 };
26 void print_stuff(const BaseClass& base_class) {
     std::cout << base_class.get_class_name() << '\n';</pre>
28 }
30 int main() {
     auto subclass = static_cast<std::unique_ptr<BaseClass>>(
       std::make_unique<SubClass>());
   std::cout << subclass->get_class_name();
```

Vtables

- Each class has a VTable stored in the data segment
 - A vtable is an array of function pointers that says which definition each virtual function points to for that class
- If the VTable for a class is non-empty, then every member of that class has an additional data member that is a pointer to the vtable
- When a virtual function is called on a reference or pointer type, then the program
 actually does the following
 - 1. Follow the vtable pointer to get to the vtable
 - 2. Increment by an offset, which is a constant for each function
 - 3. Follow the function pointer at vtable[offset] and call the function

Vtables





- Specifies to the compiler "this is not virtual for any subclasses"
- If the compiler has a variable of type SubClass&, it now no longer needs to look it up in the vtable
- This means static binding if you have a SubClass&, but dynamic binding for BaseClass&

```
1 class BaseClass {
2  public:
3   int get_member() { return member_; }
4   virtual std::string get_class_name() {
5    return "BaseClass"
6  };
7
8  private:
9  int member_;
10 }
```

```
1 class SubClass: public BaseClass {
2  public:
3   std::string get_class_name() override final {
4    return "SubClass";
5  }
6
7  private:
8   int subclass_data_;
9 }
```



Syntax	Name	Meaning
<pre>virtual void fn() = 0;</pre>	pure virtual	Inherit interface only
virtual void fn()	virtual	Inherit interface with optional implementation
void fn()	nonvirtual	Inherit interface and mandatory implementation

- Note: nonvirtuals can be hidden by writing a function with the same name in a subclass
 - DO NOT DO THIS

M Abstract Base Classes (ABCs)

- Might want to deal with a base class, but the base class by itself is nonsense
 - What is the default way to draw a shape? How many sides by default?
 - A function takes in a "Clickable"
- Might want some default behaviour and data, but need others
 - All files have a name, but are reads done over the network or from a disk
- If a class has at least one "abstract" (pure virtual in C++) method, the class is abstract and cannot be constructed
 - It can, however, have constructors and destructors
 - These provide semantics for constructing and destructing the ABC subobject of any derived classes

Pure Virtual Functions

- Virtual functions are good for when you have a default implementation that subclasses may want to overwrite
- Sometimes there is no default available
- A pure virtual function specifies a function that a class must override in order to not be abstract

```
1 class Shape {
2   // Your derived class "Circle" may forget to write this.
3   virtual void draw(Canvas&) {}
5   // Fails at link time because there's no definition.
6   virtual void draw(Canvas&);
7   // Pure virtual function.
9   virtual void draw(Canvas&) = 0;
10 };
```



Creating Polymorphic Objects

- In a language like Java, everything is a pointer
 - This allows for code like on the left
 - Not possible in C++ due to objects being stored inline
 - This then leads to slicing problem
- If you want to store a polymorphic object, use a pointer

```
1 // Java-style C++ here
2 // Don't do this.
4 auto base = std::vector<BaseClass>();
5 base.push_back(BaseClass{});
6 base.push_back(SubClass1{});
7 base.push_back(SubClass2{});
```

```
1 // Good C++ code
2 // But there's a potential problem here.
3 // (*very* hard to spot)
5 auto base = std::vector<std::unique_ptr<BaseClass>>();
6 base.push back(std::make unique<BaseClass>());
7 base.push_back(std::make_unique<Subclass1>());
8 base.push_back(std::make_unique<Subclass2>());
```



Inheritance And Constructors

- Every subclass constructor must call a base class constructor
 - If none is manually called, the default constructor is used
 - A subclass cannot initialise fields defined in the base class
 - Abstract classes must have constructors

```
1 class BaseClass {
    public:
     BaseClass(int member): int_member_{member} {}
   private:
    int int_member_;
     std::string string_member_;
8 }
10 class SubClass: public BaseClass {
    SubClass(int member, std::unique_ptr<int>&& ptr): BaseClass(member), ptr_member_(std::move(ptr)) {}
12
    // Won't compile.
14
     SubClass(int member, std::unique_ptr<int>&& ptr): int_member_(member), ptr_member_(std::move(ptr)) {}
   private:
16
     std::vector<int> vector_member_;
    std::unique_ptr<int> ptr_member_;
19 }
```



Destructing Polymorphic Objects

- Which constructor is called?
- Which destructor is called?
- What could the problem be?
 - What would the consequences be?
- How might we fix it, using the techniques we've already learnt?

```
1 // Simplification of previous slides code.
2
3 auto base = std::make_unique<BaseClass>();
4 auto subclass = std::make_unique<Subclass>();
```



Destructing Polymorphic Objects

- Whenever you write a class intended to be inherited from, always make your destructor virtual
- Remember: When you declare a destructor, the move constructor and assignment are not synthesized

```
1 class BaseClass {
    BaseClass(BaseClass&&) = default;
    BaseClass& operator=(BaseClass&&) = default;
    virtual ~BaseClass() = default;
5 }
```

Forgetting this can be a hard bug to spot



- Static type is the type it is declared as
- Dynamic type is the type of the object itself
- Static means compile-time, and dynamic means runtime
 - Due to object slicing, an object that is neither reference or pointer always has the same static and dynamic type

```
1 int main() {
     auto base class = BaseClass();
     auto subclass = SubClass();
 3
     auto sub_copy = subclass;
     // The following could all be replaced with pointers
 5
 6
     // and have the same effect.
     const BaseClass& base to base{base class};
     // Another reason to use auto - you can't accidentally do this.
 8
     const BaseClass& base to sub{subclass};
 9
     // Fails to compile
10
     const SubClass& sub to base{base class};
11
12
     const SubClass& sub_to_sub{subclass};
13
     // Fails to compile (even though it refers to at a sub);
     const SubClass& sub to base to sub{base to sub};
14
15 }
```



- Static binding: Decide which function to call at compile time (based on static type)
- Dynamic binding: Decide which function to call at runtime (based on dynamic type)
- C++
 - Statically typed (types are calculated at compile time)
 - Static binding for non-virtual functions
 - Dynamic binding for virtual functions
- Java
 - Statically typed
 - Dynamic binding

Up-casting

- Casting from a derived class to a base class is called up-casting
- This cast is always safe
 - All dogs are animals
- Because the cast is always safe, C++ allows this as an implicit cast
- One of the reasons to use auto is that it avoids implicit casts

```
1 auto dog = Dog();
2 Animal& animal = dog;
3 Animal* animal = &dog;
```

Down-casting

- Casting from a base class to a derived class is called down-casting
- This cast is not safe
 - Not all animals are dogs

```
1 auto dog = Dog();
2 auto cat = Cat();
3 Animal& animal_dog{dog};
4 Animal& animal_cat{cat};
5
6 // Attempt to down-cast with references.
7 // Neither of these compile.
8 // Why not?
9 Dog& dog_ref{animal_dog};
10 Dog& dog_ref{animal_cat};
```



How to down cast

- The compiler doesn't know if an Animal happens to be a Dog
 - If you know it is, you can use static_cast
 - Otherwise, you can use dynamic_cast
 - Returns null pointer for pointer types if it doesn't match
 - Throws exceptions for reference types if it doesn't match

```
1 auto dog = Dog();
2 auto cat = Cat();
3 Animal& animal_dog{dog};
4 Animal& animal cat{cat};
6 // Attempt to down-cast with references.
7 Dog& dog ref{static cast<Dog&>(animal dog));
8 Dog& dog_ref{dynamic_cast<Dog&>(animal_dog)};
9 // Undefined behaviour (incorrect static cast).
10 Dog& dog_ref{static_cast<Dog&>(animal_cat)};
11 // Throws exception
12 Dog& dog ref{dynamic cast<Dog&>(animal cat));
```

```
1 auto dog = Dog();
 2 auto cat = Cat();
 3 Animal& animal_dog{dog};
 4 Animal& animal cat{cat};
 6 // Attempt to down-cast with pointers.
 7 Dog* dog ref{static cast<Dog*>(&animal dog));
 8 Dog* dog_ref{dynamic_cast<Dog*>(&animal_dog));
 9 // Undefined behaviour (incorrect static cast).
10 Dog* dog_ref{static_cast<Dog*>(&animal_cat));
11 // returns null pointer
12 Dog* dog ref{dynamic cast<Dog*>(&animal cat)};
```



- Read more about covariance and contravariance
- If a function overrides a base, which type can it return?
 - If a base specifies that it returns a LandAnimal, a derived also needs to return a LandAnimal
- Every possible return type for the derived must be a valid return type for the base

```
1 class Base {
2  virtual LandAnimal& get_favorite_animal();
3 };
4
5 class Derived: public Base {
6  // Fails to compile: Not all animals are land animals.
7  Animal& get_favorite_animal() override;
8  // Compiles: All land animals are land animals.
9  LandAnimal& get_favorite_animal() override;
10  // Compiles: All dogs are land animals.
11  Dog& get_favorite_animal() override;
12 };
```



- If a function overrides a base, which types can it take in?
 - If a base specifies that it takes in a LandAnimal, a LandAnimal must always be valid input in the derived
- Every possible parameter to the base must be a possible parameter for the derived

```
1 class Base {
2   virtual void use_animal(LandAnimal&);
3 };
4
5 class Derived: public Base {
6   // Compiles: All land animals are valid input (animals).
7   void use_animal(Animal&) override;
8   // Compiles: All land animals are valid input (land animals).
9   void use_animal(LandAnimal&) override;
10   // Fails to compile: Not All land animals are valid input (dogs).
11   void use_animal(Dog&) override;
12 };
```



- Default arguments are determined at compile time for efficiency's sake
- Hence, default arguments need to use the static type of the function
- Avoid default arguments when overriding virtual functions

```
1 #include <iostream>
 3 class Base {
 4 public:
 5 virtual ~Base() = default;
 6 virtual void print_num(int i = 1) {
       std::cout << "Base " << i << '\n';
 8
 9 };
10
11 class Derived: public Base {
12 public:
     void print_num(int i = 2) override {
       std::cout << "Derived " << i << '\n';
14
15
16 };
17
18 int main() {
    Derived derived;
19
     Base* base = &derived;
20
     derived.print_num(); // Prints "Derived 2"
21
     base->print num(); // Prints "Derived 1"
22
23 }
```



Construction Of Derived Classes

- Base classes are always constructed before the derived class is constructed
 - The base class ctor never depends on the members of the derived class
 - The derived class ctor may be dependent on the members of the base class

```
1 class Animal {...}
 2 class LandAnimal: public Animal {...}
 3 class Dog: public LandAnimals {...}
 4
  Dog d;
   // Dog() calls LandAnimal()
   // LandAnimal() calls Animal()
       // Animal members constructed using initialiser list
       // Animal constructor body runs
11 // LandAnimal members constructed using initialiser list
12 // LandAnimal constructor body runs
13 // Dog members constructed using initialiser list
  // Dog constructor body runs
```

Virtuals In Constructors

If a class is not fully constructed, cannot perform dynamic binding

```
1 class Animal {...};
 2 class LandAnimal: public Animal {
     LandAnimal() {
 3
       Run();
 5
 6
     virtual void Run() {
       std::cout << "Land animal running</pre>
 8
   ";
 9
10
11 };
12 class Dog: public LandAnimals {
     void Run() override {
       std::cout << "Dog running</pre>
14
15 ";
16 }
17 };
18
19 // When the LandAnimal constructor is being called,
20 // the Dog part of the object has not been constructed yet.
21 // C++ chooses to not allow dynamic binding in constructors
22 // because Dog::Run() might depend upon Dog's members.
23 Dog d;
```

Destruction Of Derived Classes

Easy to remember order: Always opposite to construction order

```
1 class Animal {...}
2 class LandAnimal: public Animal {...}
3 class Dog: public LandAnimals {...}
4
5 auto d = Dog();
6
7 // ~Dog() destructor body runs
8 // Dog members destructed in reverse order of declaration
9 // ~LandAnimal() destructor body runs
10 // LandAnimal members destructed in reverse order of declaration
11 // ~Animal() destructor body runs
12 // Animal members destructed in reverse order of declaration.
```



- If a class is partially destructed, cannot perform dynamic binding
- Unrelated to the destructor itself being virtual

```
1 class Animal {...};
 2 class LandAnimal: public Animal {
     virtual ~LandAnimal() {
       Run();
 5
 6
     virtual void Run() {
       std::cout << "Land animal running</pre>
 8
 9
   ";
10
11 };
12 class Dog: public LandAnimals {
     void Run() override {
13
       std::cout << "Dog running</pre>
14
15 ";
16 }
17 };
18
19 // When the LandAnimal constructor is being called,
20 // the Dog part of the object has already been destroyed.
21 // C++ chooses to not allow dynamic binding in destructors
22 // because Dog::Run() might depend upon Dog's members.
23 auto d = Dog();
```

Feedback



Or go to the form here.

